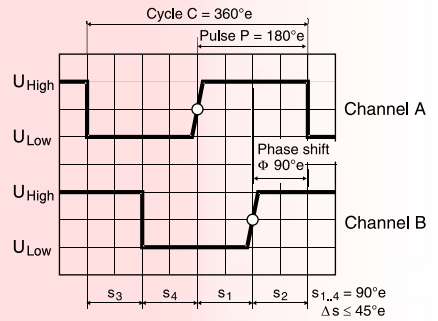
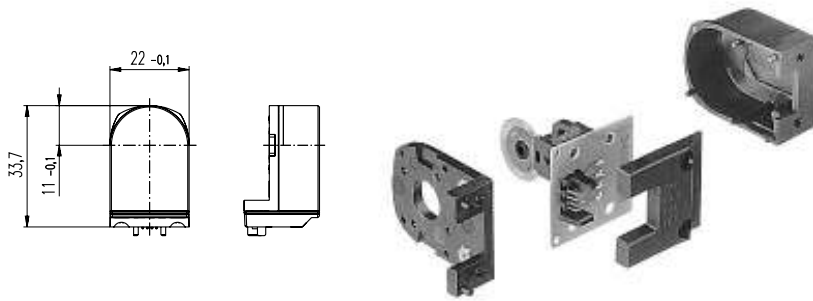


# Encoder Enc 22, 100 Counts per turn, 2 Channels

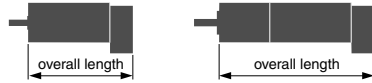


- Stock program
- Standard program
- Special program (on request)

### Order Number

103937	143330	103935	110520	168045	110521
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Type	103937	143330	103935	110520	168045	110521
Counts per turn	100	100	100	100	100	100
Number of channels	2	2	2	2	2	2
Max. operating frequency (kHz)	20	20	20	20	20	20
Shaft diameter (mm)	2	2	3	2	3	3
Orientation encoder to motor mounting defined		± 5°			± 5°	



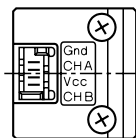
### Combination

+ Motor	Page	+ Gearhead	Page	Overall length [mm] / ● see: + Gearhead
RE 25, 10 W	76			68.6
RE 25, 10 W	76	GP 26, 0.5 - 2.0 Nm	226	●
RE 25, 10 W	76	GP 32, 0.4 - 2.0 Nm	228	●
RE 25, 10 W	76	GP 32, 0.75 - 4.5 Nm	229	●
RE 25, 10 W	76	GP 32, 1.0 - 6.0 Nm	231	●
RE 25, 20 W	78			68.6
RE 25, 20 W	78	GP 26, 0.5 - 2.0 Nm	226	●
RE 25, 20 W	78	GP 32, 0.4 - 2.0 Nm	228	●
RE 25, 20 W	78	GP 32, 0.75 - 4.5 Nm	229	●
RE 25, 20 W	78	GP 32, 1.0 - 6.0 Nm	231	●
RE 26, 18 W	79			76.2
RE 26, 18 W	79	GP 26, 0.5 - 2.0 Nm	226	●
RE 26, 18 W	79	GP 32, 0.4 - 2.0 Nm	228	●
RE 26, 18 W	79	GP 32, 0.75 - 4.5 Nm	229	●
RE 26, 18 W	79	GP 32, 1.0 - 6.0 Nm	231	●

### Technical Data

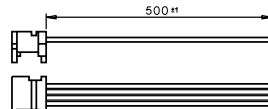
Supply voltage	5 V ± 10 %
Output signal	TTL compatible
Phase shift Φ (nominal)	90°e ± 45°e
Signal rise time (typical at C <sub>L</sub> = 25 pF, R <sub>L</sub> = 11 kΩ, 25°C)	200 ns
Signal fall time (typical at C <sub>L</sub> = 25 pF, R <sub>L</sub> = 11 kΩ, 25°C)	50 ns
Operating temperature range	-20 ... +85°C
Moment of inertia of code wheel	≤ 0.05 gcm <sup>2</sup>
Output current per channel	min. -1 mA, max. 5 mA

### Pin Allocation

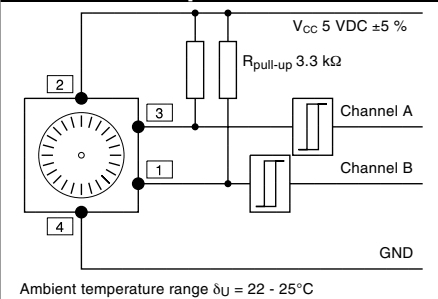


Micromodule contact strip  
Type Lumberg MICS 4  
Pin 4 GND  
Pin 3 Channel A  
Pin 2 Vcc, Pin 1 Channel B  
recommended connectors:  
Micromodule connector  
Type Lumberg MICA 4

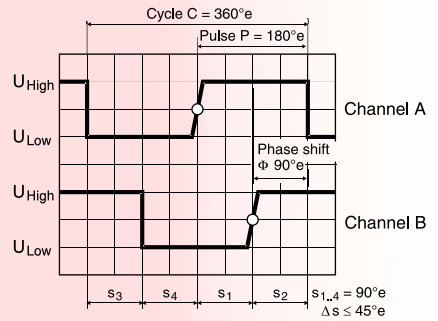
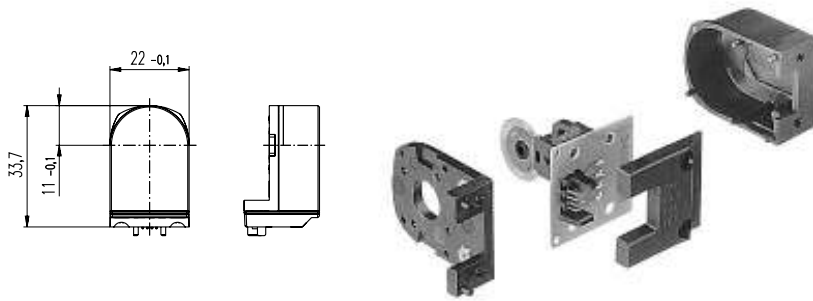
Order number for connector with cable: 3419.506



### Connection example



# Encoder Enc 22, 100 Counts per turn, 2 Channels

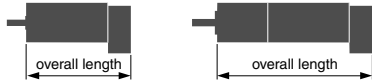


maxon tachometer

- Stock program
- Standard program
- Special program (on request)

Order Number						
103937	143330	103935	110520	168045	110521	

Type	103937	143330	103935	110520	168045	110521
Counts per turn	100	100	100	100	100	100
Number of channels	2	2	2	2	2	2
Max. operating frequency (kHz)	20	20	20	20	20	20
Shaft diameter (mm)	2	2	3	2	3	3
Orientation encoder to motor mounting defined		± 5°			± 5°	



Combination				Overall length [mm] / ● see: + Gearhead
+ Motor	Page	+ Gearhead	Page	
F 2130, 3 W	91			45.0
F 2130, 3 W	91	GS 30, 0.07 - 0.2 Nm	227	●
F 2140, 6 W	94			65.5
F 2140, 6 W	94	GS 38, 0.1 - 0.6 Nm	234	●
A-max 19, 1.5 W	106			43.3
A-max 19, 1.5 W	106	GP 19, 0.1 - 0.3 Nm	217	●
A-max 19, 1.5 W	106	GS 20, 0.06 - 0.25 Nm	218	●
A-max 19, 1.5 W	106	GP 22, 0.1 - 2.0 Nm	219-222	●
A-max 19, 1.5 W	106	GS 24, 0.1 Nm	225	●
A-max 19, 2.5 W	108			45.9
A-max 19, 2.5 W	108	GP 19, 0.1 - 0.3 Nm	217	●
A-max 19, 2.5 W	108	GS 20, 0.06 - 0.25 Nm	218	●
A-max 19, 2.5 W	108	GP 22, 0.1 - 2.0 Nm	219-222	●
A-max 19, 2.5 W	108	GS 24, 0.1 Nm	225	●
A-max 22	110/112			46.3
A-max 22	110/112	GP 22, 0.1 - 0.3 Nm	219	●
A-max 22	110/112	GP 22, 0.2 - 0.6 Nm	220	●
A-max 22	110/112	GP 22, 0.1 - 2.0 Nm	219-222	●
A-max 22	110/112	GS 24, 0.1 Nm	225	●
A-max 26	114-120			59.1
A-max 26	114-120	GP 26, 0.5 - 2.0 Nm	226	●
A-max 26	114-120	GS 30, 0.07 - 0.2 Nm	227	●
A-max 26	114-120	GP 32, 0.4 - 2.0 Nm	228	●
A-max 26	114-120	GP 32, 0.75 - 4.5 Nm	229	●
A-max 26	114-120	GP 32, 1.0 - 6.0 Nm	232	●
A-max 26	114-120	GS 38, 0.1 - 0.6 Nm	234	●

Technical Data	
Supply voltage	5 V ± 10 %
Output signal	TTL compatible
Phase shift $\Phi$ (nominal)	90° ± 45°
Signal rise time (typical at $C_L = 25$ pF, $R_L = 11$ k $\Omega$ , 25°C)	200 ns
Signal fall time (typical at $C_L = 25$ pF, $R_L = 11$ k $\Omega$ , 25°C)	50 ns
Operating temperature range	-20 ... +85°C
Moment of inertia of code wheel	≤ 0.05 gcm <sup>2</sup>
Output current per channel	min. -1 mA, max. 5 mA

